



# Outline

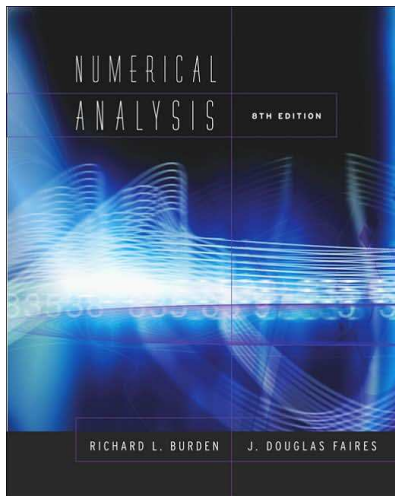
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- 5 Application
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# Contact Information



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Phone	(619)594-3743
Office Hours	MW: 1 – 2, 3 – 4), and by appointment

## Basic Information: The Book



**Title:**  
*"Numerical Analysis,"*  
**8th Edition**

**Authors:**  
Richard L. Burden &  
J. Douglas Faires

**Publisher:**  
Thomson – Brooks/Cole

**ISBN:**  
**0-534-39200-8**

# Basic Information: Syllabus

Chapter	Title
1	Mathematical Preliminaries
2	Solutions of Equations in One Variable
3	Interpolation and Polynomial Approximation
4	Numerical Differentiation and Integration
6	Direct Methods for Solving Linear Systems
8	Approximation Theory
7	Iterative Techniques in Matrix Algebra
<b>Math 542:</b>	<b>Numerical Solutions of Differential Equations</b>
5	Initial-Value Problems for ODEs
11	Boundary Value Problems for ODEs
<b>Math 543:</b>	<b>Numerical Matrix Analysis</b>
7	Iterative Techniques in Matrix Algebra
9	Approximating Eigenvalues
<b>Math 693a:</b>	<b>Advanced Numerical Analysis (Numerical Optimization)</b>
10	Numerical Solution of Nonlinear Systems of Equations
<b>Math 693b:</b>	<b>Advanced Numerical Analysis (Numerics for PDEs)</b>
12	Numerical Solution of PDEs





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  - Abide by university statutes, and all applicable local, state, and federal laws.



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- Students are expected **and encouraged** to to make use of office hours! If you cannot make it to the scheduled office hours: contact the instructor to schedule an appointment!

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- How to open a ROHAN account:  
<http://www-rohan.sdsu.edu/raccts.shtml>
- You may also want to consider buying the student version of Matlab: <http://www.mathworks.com/>

# Math 541: Formal Prerequisites

I of II

Math 254, or Math 342A

254  $\Rightarrow$  **Introduction to Linear Algebra**

- Matrix Algebra, Gaussian elimination, determinants, vector spaces, linear transformations, orthogonality, eigenvalues and eigenvectors.

342A  $\Rightarrow$  **Methods of Applied Mathematics, I**

- Vector analysis, divergence and Stokes' theorem, integral theorems. Matrix analysis, eigenvalues and eigenvectors, diagonalization. Introduction to ODEs. Computer software for matrix applications, solving, and graphing differential equations.



## 11 of 11

106  $\Rightarrow$  Intro to Programming: FORTRAN

- 107  $\Rightarrow$  **Intro to Programming: JAVA**

- ## 205 ⇒ Intro to Programming and Visualization

- Problem solving skills for science, computing/software tools of computational science, computer communications, programming and visualization.

# Math 541: Course Design

- Professor Joe Mahaffy thanks Professors Peter Blomgren and Don Short for extensive access to their experience and notes for this course.
- I will borrow heavily, edit, and post on the web the notes and homework assignments created from these past instructors, especially Peter Blomgren.



# Math 541: Introduction — Why???

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A: To accurately approximate the solutions of problems that cannot be solved exactly.

Q: What kind of applications can benefit from numerical studies?

A: Engineering, physics, chemistry, computer, biological and social sciences.

Image processing / computer vision, computer graphics (rendering, animation), climate modeling, weather predictions, “virtual” crash-testing of cars, medical imaging (CT = Computed Tomography), AIDS research (virus decay vs. medication), financial math





# Math 541: Introduction — Computing Efficiency

Numerical tools for problem solving:

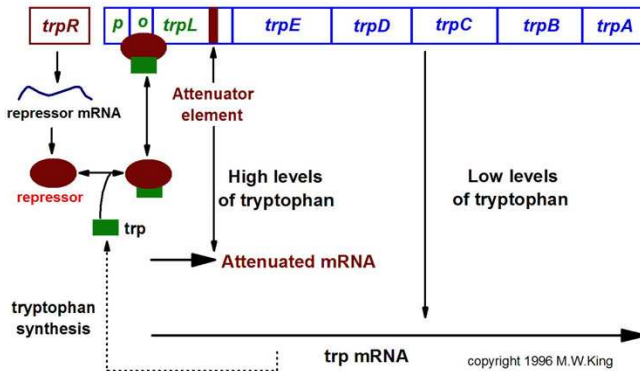
- Computers are getting faster, but the computer's speed is only one (a big one for sure!) part of the overall performance for a computation...
- Computing speed depends on **FLOPS** (floating-point operations or number of additions and multiplications) and **memory accesses**. These are largely questions of computer architecture and won't be examined in this course much.
- Numerical Algorithms are the center of this course, and their efficiency affects performance.



# Research Problem from my Work

## Genetic Control by Repression

### Structure of the *trp* Operon



## Model for Control by Repression

Let  $x_1(t)$  be the concentration of mRNA and  $x_2(t)$  be the concentration of the tryptophan (endproduct). This process is often called endproduct inhibition, and it is a negative feedback system. These systems, especially with delays, can result in oscillatory behavior.

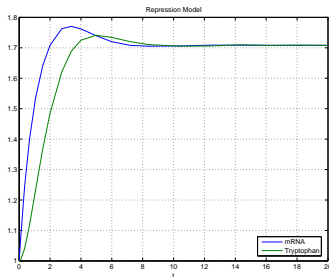
$$\begin{aligned}\frac{dx_1(t)}{dt} &= \frac{a_1}{1 + kx_2^n(t - R)} - b_1x_1(t) \\ \frac{dx_2(t)}{dt} &= a_2x_1(t) - b_2x_2(t)\end{aligned}$$

This is a system of first order delay differential equations, which is infinite dimensional because of the need for initial data including a history of the solution on the interval  $[-R, 0]$ .

# Simulation of Repression Model

Simulated model with  $a_1 = 2$ ,  $a_2 = b_1 = b_2 = 1$ ,  $n = 4$ , and  $R = 2$ .

MatLab simulation uses package DDE23. You will study a related algorithm in Math 542, the Runge-Kutta-Felberg method for integrating ordinary differential equations (numerically solving the ODE).



# Equilibrium Analysis

- Qualitative analysis of any differential equation begins with finding all equilibria for the system.
- The equilibria are found by solving the derivatives equal to zero.

$$\begin{aligned}\frac{a_1}{1 + k\bar{x}_2^n} - b_1\bar{x}_1 &= 0 \\ a_2\bar{x}_1 - b_2\bar{x}_2 &= 0\end{aligned}$$

- This gives a system of nonlinear equations equal to zero, which usually require numerically methods to approximate the equilibria. Here it easily reduces to a nonlinear scalar equation,  $f(x) = 0$ , which early in this course, we learn to solve.

$$\frac{a_1}{1 + k\bar{x}_2^n} - \frac{b_1 b_2}{a_2} \bar{x}_2 = 0 \quad \text{with} \quad \bar{x}_1 = \frac{b_2}{a_2} \bar{x}_2$$

# Characteristic Equation

- The characteristic equation is used to study the local (linear) behavior near an equilibrium.
- The characteristic equation for delay differential equations is found like one does for ordinary differential equations (Math 537), but the result is an exponential polynomial with an infinite number of solutions.

$$\begin{vmatrix} -b_1 - \lambda & f'(\bar{x}_2)e^{-\lambda R} \\ a_2 & -b_2 - \lambda \end{vmatrix} = 0$$

$$(\lambda + b_1)(\lambda + b_2) - a_2 f'(\bar{x}_2)e^{-\lambda R} = 0$$

Need to find complex solutions to this equation.

# Characteristic Equation—Finding Eigenvalues

- The numerical simulation showed damped oscillations which suggests that all eigenvalues have negative real part.
- The characteristic equation is studied by letting  $\lambda = \mu + i\nu$ , which gives

$$(\mu + i\nu + b_1)(\mu + i\nu + b_2) - a_2 f'(\bar{x}_2) e^{-\mu R} (\cos(\nu R) - i \sin(\nu R)) = 0$$

- This is solved numerically by simultaneously finding the real and imaginary parts equal to zero. Solving two nonlinear equations in two unknowns uses vector and matrix methods to extend our technique for solving  $f(x) = 0$ . We may get to these algorithms in this class, but they certainly appear in Math 693A.



# Characteristic Equation—Numerical Eigenvalues

- This course examines some of the basics behind the packages for solving these problems. **MatLab** allows users to examine the coding algorithm, so knowledge from this course helps you better choose amongst different packages.
- We employed Maple's **fsolve** routine, and the first three pairs of eigenvalues with the largest imaginary parts are found.

$$\lambda_{1,2} = -0.19423 \pm 0.98036i$$

$$\lambda_{3,4} = -0.55573 \pm 3.9550i$$

$$\lambda_{5,6} = -0.068084 \pm 7.07985i$$

These eigenvalues show the damped oscillatory behavior and indicate the intervals between maxima are about  $2\pi$  time units.

Maple code available from Website.